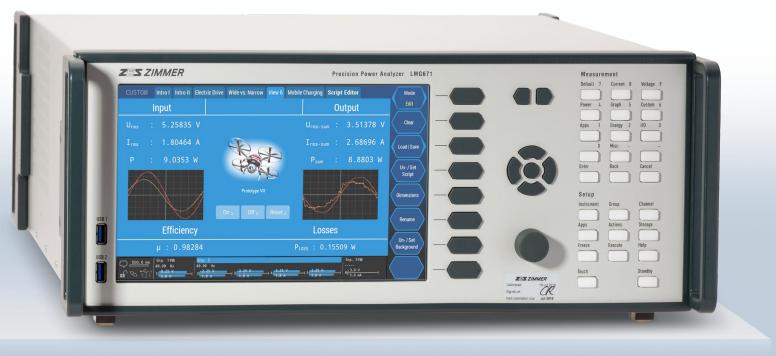


## LMG671 Precision Power Analyzer



## Getting precise results does not have to be complicated

### ZES ZIMMER - four decades in power analysis

Analyzing power is not just something we do – it is the very heart of ZES ZIMMER's mission and always has been. For almost four decades we have dedicated ourselves to finding the most precise and reliable way to measure electric power, efficiencies and losses for single and multi-phase applications. Since the company's establishment in 1980, we design and manufacture precision power analyzers at our company's headquarter near Frankfurt, Germany, and ship them to customers all around the globe.

The electric and electronics industry uses our LMG power analyzers in R&D and for quality assurance, test labs employ them to guarantee compliance with standards, and universities rely on them to train future generations of engineers and scientists. Our clients' experience in their own applications helps us to make sure every new product is even better than the previous one, making our users' life easier, solving their problems faster, better, and in a more convenient way.

We listen to you, and this is why we keep coming up with innovative features that have rapidly been adopted by the industry and also inspired other manufacturers:

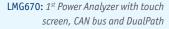
- 1<sup>st</sup> power analyzer with color display
- 1<sup>st</sup> power analyzer with logical group concept (p. 14)
- 1<sup>st</sup> power analyzer with independent sync on multiple channels
- 1<sup>st</sup> Plug 'n' Measure power analyzer (p. 6)

- 1<sup>st</sup> 8-channel power analyzer
- 1<sup>st</sup> power analyzer with touchscreen GUI
- 1<sup>st</sup> power analyzer featuring unique
  DualPath architecture (p. 5)
- 1<sup>st</sup> power analyzer with CAN bus interface (p. 11)

Adding features is important to help our customers cope with the increasingly demanding measurement challenges they are facing, but is also crucial to make sure the resulting complexity does not distract and confuse rather than help. We have found a unique way out of this dilemma, you can learn more about our adaptive GUI on p. 13. Of course, the instrument is only half the story. Every application is unique. Do you have to worry about common-mode influence? Is the result still reliable for power factors approaching 0.01? Is the earth capacitance low enough to avoid interference by leakage currents? How to calculate measurement uncertainty? The same experience that helps us conceive superior power analyzers can help you find the best way to measure. We know your power measurement challenges inside out, because we have been there and know how to put ourselves in your shoes. We think power 24/7, and we are happy to share our knowledge with you – don't hesitate to get in touch.

ZES ZIMMER's mission is to enable you to get fast, precise and reliable results – our time-proven technology and our decade-long experience in power analysis provide all it takes!





#### 2014

2019



LMG500: 1<sup>st</sup> Power Analyzer with eight measurement channels, independent sync and Plug 'n' Measure

2005



LMG450: 1<sup>st</sup> Power Analyzer with logical group concept

2000



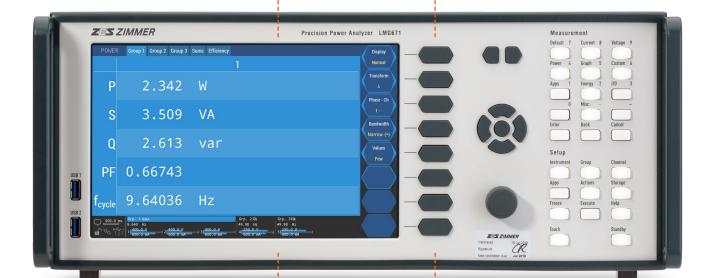
## LMG671 – powerful, convenient, flexible

# Pushing the limits

- $\checkmark$  Measuring standby currents in the  $\mu$ A range and up to 32 A
- ✓ Market-leading analog bandwidth of 10 MHz
- ✓ Unique DualPath architecture eliminates aliasing dilemma
- ✓ Best-in-class accuracy

### Easy data exchange

- ✓ Collect data from any analog or digital sensor
- ✓ Plug into CAN bus to blend into automotive environment
- ✓ Continuously stream sample values for advanced post-processing
- ✓ Run our sophisticated analysis suite on captured data



### Fits to your task

- Configure the number and kind of your power channels for the best price and performance
- ✓ Sync to different frequencies on each channel group
- ✓ Focus on the relevant signal content with highly versatile filters
- Customize your analysis in content ✓ and appearance

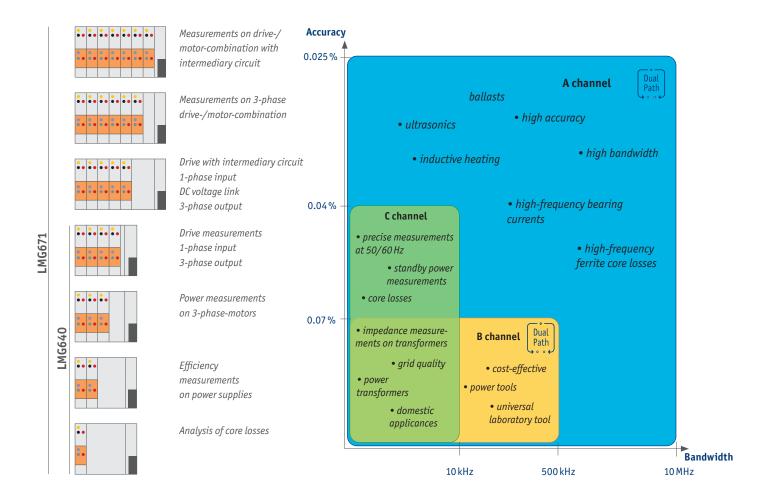
### Barrier-free measurements

- ✓ Quickly familiarize yourself with our touchscreen GUI
- ✓ Adapt it to your own needs with a few clicks
- ✓ Enhance your screenshots with
  ✓ on-screen comments and sketches
- ✓ Add sensors using Plug'n'Measure

#### The right channel combination for every application

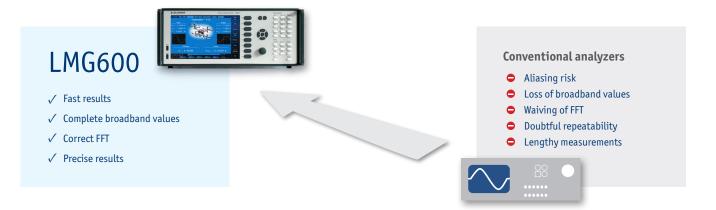


Power analyzers are available in different accuracy classes, to allow the user to choose the right tool for the job at hand. After all, not all applications require maximum precision; often lower resolution and frequency range are sufficient. Unfortunately, not all measuring applications exhibit this distinction. It is very well possible, for instance, to have need for different frequency ranges and accuracy levels at different points in the same measurement configuration. This is why the LMG600 offers three different channel types, which can be combined in the same chassis without problems to ensure that you always have a measuring device tailored to your needs for your particular application. No need to accept trade-offs in accuracy or take a sledgehammer to crack a nut, if a lower priced solution could have served your purposes equally well.

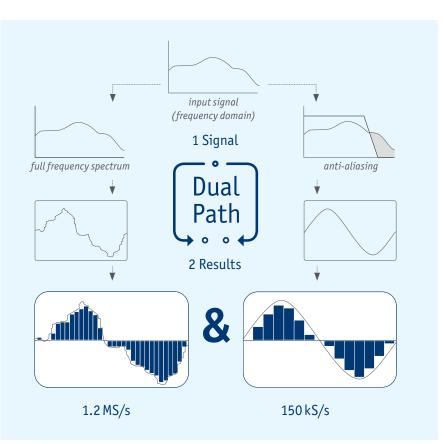


### Measuring in two bandwidths at the same time, thanks to DualPath - no compromises, no doubts

On conventional power analyzers, a signal undergoes analog conditioning, followed by optional anti-aliasing filters, before being fed into an A/D converter. The resulting signal can afterwards be used for the calculation of cycle-based RMS values. Alternatively it can serve as the base for an FFT or further digital filtering. Due to the limitation of using a single A/D converter, there are inherently some downsides to be factored in with conventional devices. If measurements are carried out with filters active, in order to avoid aliasing with FFTs, then the wideband values are lost. With the filters switched off, strictly speaking, FFTs should not be used. If, in spite of this, FFTs are used without an anti-aliasing filter for measurements across the full frequency range, then the quality of the calculated values is questionable. An aliasing error of 50%, for instance, is easily detected, however a deviation of 0.5 % could go unnoticed. Ultimately, when you alternate filtered and non-filtered measurements, the validity of the results is equally in question, as this involves the assumption that the signal does not change over time, which is in practice hardly ever the case. In addition, this procedure is especially time consuming.



In the end, all of the measurement methods presented above are merely unsatisfactory compromises. This is why ZES ZIMMER has fundamentally redesigned signal processing and developed the DualPath architecture. The analog side is the same as in conventional measuring devices, however the subsequent digital processing has been revolutionized. The LMG600 is the first power analyzer to have two A/D converters in two independent signal paths for each current and voltage channel. One, for the filterless measurement of the wideband signal, and another, for the narrowband signal at the output of the anti-aliasing filter. The parallel processing of the digitized sample values gives the user access to both measurements of the same signal, without risking aliasing effects. This unique procedure avoids all of the downsides of previous approaches and guarantees the most precise result in the shortest time possible.



#### Gapless/zero-blind measurement

In the course of stricter monitoring of the consumption and efficiency of electrical devices, new standards and procedures are continuously being introduced (e.g. SPECpower\_ssj2008, IEC 62301, EN 50564), in order to enable an impartial comparison of products from different manufacturers. Be it an office computer, server or household appliance, the same principle applies: the procedure always requires long term analysis of the power consumption, taking into account all relevant operating conditions. The differences between minimum load - e.g. in standby - and full load can be of a significant magnitude, which makes precise measurement very challenging (see also application report no. 102 <u>"Mea-</u> <u>surement of standby power and energy</u> efficiency" at www.zes.com). Some of the measurements required must be performed over several hours, yet without gaps. By selecting a sufficiently high measurement range, changing ranges and the inevitably associated losses in data can be avoided. The high basic accuracy of the LMG600 ensures precise measurement results, even near the lower limit of a range.

#### Precise measurements thanks to minimal delay differences

The fast-switching semiconductors used in modern frequency converters to improve efficiency produce extremely steep voltage edges. The resulting capacitive currents put strain on the bearings and the insulation of the motors – this can lead to premature failure.

Motor filters (e.g. dU/dt filters) attenuate the steep voltage gradient, although they generate power losses themselves due to the transient oscillation with the filter's own frequencies (typically > 100 kHz). The broad frequency range and the minimal delay between current and voltage on the LMG600 allow extremely precise power loss measurements on the filters at these frequencies, including longitudinal measurements at low power factors. This also applies to power measurements with high frequency ranges of up to 10 MHz, which require the current and voltage channels to be designed for the smallest delay differences. On the LMG600 the offset is less than 3 ns, corresponding to a phase error <1 µrad at 50 Hz. This makes the devices best suited to measure the power losses at low phase angles for transformers, chokes, capacitors and ultrasonic generators. No additional options or adjustments are required; the LMG600 is already fully capable of this measurement task with the standard factory settings. Usually current and voltage transducers are used for measurements on high-power circuits. The phase angle of these transducers can be corrected to improve measurement accuracy.

#### Range extension with sensors? Plug 'n' Measure!

Although the LMG600 offers unmatched dynamic range, both for voltage and current, there are always applications with extraordinary requirements in terms of measurement ranges. Whether you are dealing with currents of several hundred amps or voltages of several kilovolts, ZES ZIMMER has the right solution at the ready. We offer a wide range of current and voltage sensors, which work perfectly in unison with the LMG600 precision power analyzer and extend the measurement ranges of the device by the required amount. The sensors of our Plug 'n' Measure series are equipped with a bus system, which enables automatic configuration of the LMG600. This allows for all of the important parameters, such as the precise scaling factor, the delay compensation variable, the last calibration date, and the sensor type, to be read and used automatically by the power analyzer. Moreover, the sensors are actively supplied with power by the LMG600, separate power supplies are no longer required.

With Plug 'n' Measure there is no need for fine tuning by the user to improve the results. There is no difference between direct and sensor-supported measurements. Of course, other commercially available sensors can also be used with the LMG600.



Sensor Type PCT

### **Powerful interfaces**

In test bench environments, the power analyzer often must share its measurements with other existing computer and software environments.

As the high sampling rate of the LMG600 inevitably creates a large amount of data, we equipped it with a powerful Gigabit ethernet LAN interface to avoid bottlenecks. Even high-resolution measurements of all important parameters, such as current, voltage, active power, etc. over a period of several minutes or even hours can be rapidly transferred to a connected computer.

In automotive environments CAN bus is widely used. By choosing the LMG600's CAN bus option, measurements can directly be shared over CAN, and the LMG600 can in turn act on data received over CAN (details on p.11).

Other interfaces are useful to connect peripheral devices for input or visual output. A USB 3.0 slot is available, and the LMG600 can also be equipped with a DVI interface to connect an external monitor or projector. Two more slots can be retrofitted for future interface standards. The integrated sync interface allows to precisely synchronize multiple LMG600 with one another. It creates a common time base for measurements involving multiple LMG600 on the same system, or the mutual connection and control of an LMG600 by oscilloscopes or waveform generators. The internal SSD of the LMG600 can store measured values, settings, user-defined measurement variables, or graphs for later use, even without having a PC connected. The firmware of the LMG600 can be quickly and easily updated via USB.



#### Process signal interface (PSI)

#### In-/Outputs

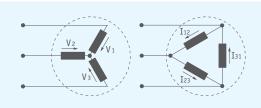
- ✓ 2 fast, synchronized analog inputs (ca. 150 kS/s)
- ✓ 8 analog inputs
- ✓ 8 switching inputs (ca. 150 kS/s)
- ✓ 2 torque-/speed-/ frequency inputs
- ✓ 32 analog outputs
- ✓ 8 switching outputs

It is often necessary to take further measurements in addition to electrical parameters to be able to make a meaningful overall statement on the performance and efficiency of the device being tested. Hence, it is vital to be able to perfectly synchronize these measured values with the RMS values calculated by the LMG600, in order to establish reliable timing between electrical and mechanical events. A typical application is the analysis of electrical drive systems, where torque and speed must be measured and reconciled with the

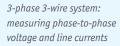
electrical parameters. Conversely, it may also be necessary for the power analyzer to output results as analog signals for further processing, or to trigger switching operations depending on measured variables or derived values. In order to be equipped for all of these potential requirements, the LMG600 offers a multitude of different input/output features for analog and digital signals.

#### Star-to-delta conversion

In three-phase three-wire systems, only the line-to-line voltages  $U_{12}$ ,  $U_{23}$ ,  $U_{31}$  and the line currents  $I_1$ ,  $I_2$ ,  $I_3$  are accessible for measurement. With the star-to-delta conversion option, the line-to-line voltages can be converted to non-accessible phase voltages and the related active power can be determined. Likewise the line currents can be converted into the phase currents. From these calculated values it is possible to derive all other variables, such as harmonics. Distortions and imbalances of the grid or consumers are properly taken into account. This makes the use of an external, artificial neutral point superfluous;



although one could use such at any time, provided that the associated disadvantages (e.g. increased power losses) are taken into account.

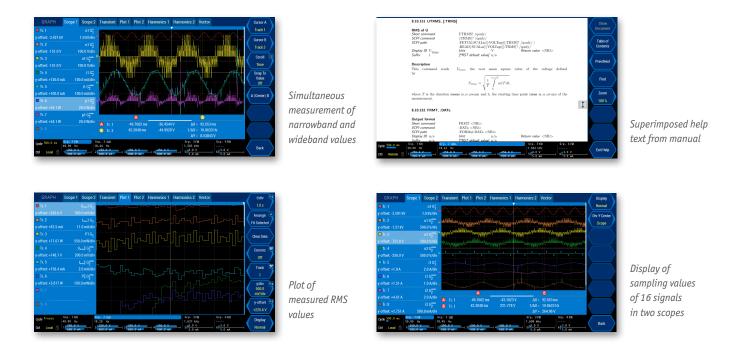


#### Easy to use – with or without touchscreen

To ensure that the LMG600 can be used in all conditions, particular attention has been paid to universal usability. All display modes and setting options can be operated both by the touchscreen or the keypad, without exception. The optimized design consistently links the keypad to the associated views and setting options on the screen. To use the instrument effectively requires almost no familiarization. The graphical user interface directs the user without detours to the required values. Be it RMS of voltage or current, associated harmonics or cumulative values, these are usually only a single press of a button away. In addition, user-defined views allow to group individually measured values, so that all the parameters are always available at a glance. This ergonomic way of operation and the associated time savings contribute directly to the productive use of the LMG600. The eight context-specific double softkeys to the right of the display, whose function always corresponds to their on-screen counterparts on the right-hand side, are especially important for ease-ofuse. One can determine the function as-



signed to a given softkey at a glance. The double softkey design enables the respective parameter to be rapidly configurable; switching through views that are not relevant is no longer necessary. Should there be questions about function and control while operating the device, the relevant sections of the manual can be displayed at any time.



### Everything important just a click away

Click on softkey <Display> to toggle between RMS values and harmonics

|       |       |               |     | (All C                 | hannels) |     | (All Channels)           |     |             | Harmonics  |
|-------|-------|---------------|-----|------------------------|----------|-----|--------------------------|-----|-------------|------------|
|       |       |               |     | f <sub>h</sub> 0.0     |          | f1  |                          |     |             | Transform  |
|       |       |               |     |                        |          |     |                          |     |             | *          |
|       |       |               |     |                        |          |     |                          |     |             | Phase - Ch |
|       |       |               | U 1 |                        |          | U 2 |                          | U 3 |             | All        |
| 00    | -0.   | 008           | V   |                        | 0.020    | V   | -0.012                   | ۷   |             | Harmonics  |
| 01    | 0.    | 030           | V   |                        | 0.021    | ۷   | 0.009                    | ۷   |             | Odd & Ever |
| 02    |       |               |     |                        | 0.012    |     | 0.002                    |     |             | Values     |
| 03    |       | 025           |     |                        | 0.014    |     | 0.040                    |     |             | U          |
| 10    |       | 775           |     |                        | 47.734   |     | 47.753                   |     |             |            |
| 11    |       | 045           |     |                        | 0.040    |     | 0.016                    |     |             |            |
| 12    |       |               |     |                        | 0.009    |     | 0.023                    |     |             |            |
| 13    |       | 010           |     |                        | 0.007    |     | 0.018                    |     |             |            |
| e 200 | .0 ms | Grp.<br>50.00 |     | Grp. 2 U∆I<br>18,40 Hz |          |     | Grp. 3 Filt<br>1.462 kHz |     | Grp. 4 Filt |            |

| DEF               | FAULT Group 1 Group 2 | Group 3 Group 4 Sums   |                                 |             | Display                  |
|-------------------|-----------------------|--|---------------------------------|-------------|--------------------------|
|                   |                       |  | 3                               | Σ           | Normal                   |
| U <sub>trms</sub> |                       | 85.898 V   | 85.917 V                        | 148.807 V   | Transform                |
| I <sub>trms</sub> | 91.670 mA             | 90.536 mA  | 89.056 mA                       | 0.15663 A   | Phase - Ch 🗉<br>All      |
| P                 | 1.9493 W              | 1.8981 W   | 1.9488 W                        | 5.79625 W   | Bandwidth<br>Wide (====) |
| PF                | 0.24748 ind           | 0.24407 ind  | 0.25470 ind                     | 0.24869     | Values<br>Few            |
| s                 | 7.8767 VA             | 7.7769 VA  |                                 | 23.3068 VA  |                          |
|                   | 7.6317 var            | 7.5417 var   | 7.3991 var                      | 22.5746 var |                          |
|                   |                       | Grp. 2 UAJ<br>18.43 Hz<br>2 (250.0 V<br>600.0 mA<br>3 (250.0 V<br>600.0 mA | Grp.<br>1.586<br>5-3.0<br>5-5.0 | kHz         | -                        |

Click on softkey <Phase-Ch> to display measured values for all channels or linked values in a group

Normal

Group

Bandwidth

Narrow (+)

Values Few



Click on Cycle to set the duration and the reference of the measurement cycle

Click on the group to change the signal, harmonics and synchronization settings

Ρ

S

Q

PF

f<sub>cycle</sub>

ycle -

Ctri Local 🔒

Click on the level indicator to configure the channel-specific measurement ranges and sensor settings

Group 1 Group 2 Group 3 Group 4 Sums Efficiency

W

VA

var

Hz

12.1070

25.6706

22.6363

0.47163

49.9977

Grp. 2 UΔ 18 41 Hz

Grp. 1 Filt 50.00 Hz Group 1



|                |   |          |                          | Group      |
|----------------|---|----------|--------------------------|------------|
| Auto Range     | Auto  |          |                          | Channel    |
| Jack           |   |          |                          | 2          |
| Sensor         |   |          |                          | Select I/U |
| Range          |   |          |                          | U          |
|                |   |          |                          | Auto Range |
|                |   |          |                          | Auto       |
| Auto Range     | Auto  | Auto     | Auto                     | Jack<br>U* |
| Jack           |   |          |                          | Sensor     |
| Sensor         | Default                                     | Default  | Default                  | Default    |
| Range          | 600.0 mA                                    | 600.0 mA | 600.0 mA                 | Range      |
|                |   |          |                          | 250.0 V    |
| Cycle 500.0 ms | Grp. 1 Filt Grp. 2 UAJ<br>50.00 Hz 18.42 Hz |          | Grp. 3 Filt<br>1.487 kHz |            |

Grp. 3 Filt 1.549 kHz

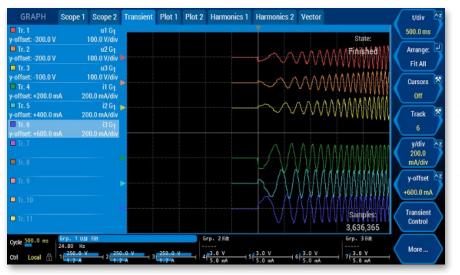
6 3.0 V

#### Capturing important events on scope

Steady-state measurements are making up a considerable portion of power analyzers' everyday use scenarios. Still, it is often the unpredictable events that give design engineers a headache. Reliable detection of transient conditions imposes heavy demands on the instruments used.

Whenever supreme accuracy, low measurement ranges, direct current measurement and robust electrical isolation are required, oscilloscopes and transient recorders have to cede to power analyzers. ZES ZIMMER's LMG600 series power analyzers can be equipped with the Event Trigger software option (L6-OPT-EVT) to monitor voltage and current signals for unique conditions. Those conditions can be characterized by upper and lower bounds of the sample values, which can also be combined to define signal windows for triggering.

After trigger conditions have been set, ZES ZIMMER's Trigger View offers a convenient way to verify the correctness of the settings. Trigger View visualizes the effects of settings like sync filters and level or hysteresis and displays the resulting trigger signal. Once the defined conditions are violated for the minimum duration chosen by the customer, recording is activated. The length of the recording can be chosen by the user, with 16 tracks at 16MS (LMG670: 4MS) each available for storage. The recorded samples are available graphically on the LMG600's scope in a separate tab, or numerically via the data interfaces for further analysis. Using the event trigger function has no impact on cycle based power measurements carried out in parallel on the same channel.

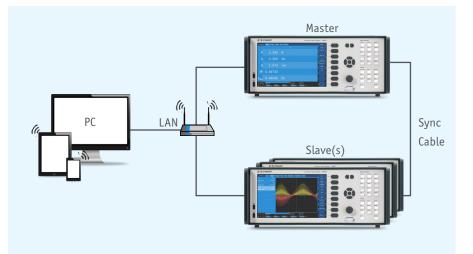


Screenshot of Event Trigger option with up to 16 million samples. The Scope View offers a quick and convenient way to visualize signals in the time domain. The viewer for the Event Trigger allows you to display the behavior of voltage, current, power or other variables in 16 tracks from different channels in graphical form and with a variable time base. Cursors can be used to mark segments or measure differences of time and amplitude between two points. The reciprocal value of the time difference (i.e. frequency) is also provided. Further analysis of the samples can be performed on PC using the LMG Sample Vision software.

#### Synchronization - no need to stop at 7 channels

The LMG600 series already offers the highest channel count per chassis in the power analyzer market, yet there are applications which require 8 or more points of power measurement. The solution is simple: combine multiple LMG600 chassis' to create a virtual power analyzer with more channels. All you need to do is to connect the individual units via sync cable, and they will automatically synchronize:

- ✓ cycle timing
- ✓ system time
- ✓ transient trigger events
- $\checkmark$  state of energy integration



### Bi-directional CAN interface – remote control via CAN

In many test setups involving power analysis, the majority of the data to be evaluated will come from the power analyzer itself. The automotive environment, however, typically differs a lot. Modern cars can be equipped with hundreds of electronic control units (ECUs) and sensors of different kinds. Within the sea of data points these devices generate, voltage, current and power values are just a minor subset. Nevertheless, this subset needs to be integrated with the remainder of the data for the test engineers to benefit from it.

While ECU and sensor data typically get exchanged over the CAN bus, traditional power analyzers communicate via GPIB or Ethernet. Thus, it is up to the test engineers to reconcile data from both sources and to put it in a common format in order to correlate it. This is no mean feat, as there is usually no common time basis between the CAN data and the values provided by the power analyzer, and matching electrical parameters to other sensor data is very challenging. In any case, there is a lot of manual intervention involved, and the procedure is cumbersome, lengthy and error-prone.

The LMG600 is the only dedicated power analyzer in the world that is able to share up to 128 values and variables over CAN bus. This unique capability helps to bridge the gap between the automotive industry's most popular field bus and traditional test & measurement equipment. Test engineers can now read voltage, current, power etc. the same way they read speed, torque, temperature and other variables: by gathering data from sources on the CAN bus. No sep-

| INSTR.    | Measuring     | General Interfa  | ce PSI CAN | GPIO & Sync | Options/Key |            |       |
|-----------|---------------|------------------|------------|-------------|-------------|------------|-------|
| ransmit T | rigger Global | Settings / Misc. |            |             |             |            |       |
| Id        | EFF           | Offset           | Bit Length | Ор. Туре    | Condition   | Ref. Value | State |
| 10        | Off           |                  |            | INTEGER     | GREATER     | 28         | ON    |
|           | Action :      | logonce          |            |             |             |            |       |
|           | Off           |                  |            | INTEGER     | GREATER     | 28         | ON    |
|           | Action :      | logonce          |            |             |             |            |       |
|           | On            |                  |            | INTEGER     | NEQUAL      |            | OFF   |
|           | Action :      |                  |            |             |             |            |       |
| 0         | Off           | 0                | 0          | INTEGER     | NEQUAL      | 0          | OFF   |

|                             | INSTR. Measur      | ing General Interface  | PSI CAN GPIO&S | ync Options/Key        |        |
|-----------------------------|--------------------|------------------------|----------------|------------------------|--------|
| 1                           | Transmit Trigger G | lobal Settings / Misc. |                |                        |        |
|                             | Slot               | CAN Id                 | EFF Bit        | Measurand              | Status |
|                             |                    |                        |                |                        |        |
|                             | 2                  | 16                     | On             | U <sub>trms</sub> 1 G1 | ON     |
|                             |                    |                        |                | I <sub>trms</sub> 1 G1 |        |
|                             |                    |                        | On             | lh1 G1 (1)             | ON     |
|                             |                    |                        |                | EP1 G1                 |        |
|                             |                    | 20                     | Off            | PF1 G1                 | ON     |
|                             |                    |                        |                | PSIM <sub>TORQUE</sub> |        |
| Define the                  |                    |                        | On             | PSIM <sub>SPEED</sub>  | ON     |
| asurands sent<br>to CAN bus |                    |                        |                | Transient 0, (1)       | ON     |

arate treatment, no extra work, no distinct data repositories. The necessary time to integrate power measurements into the overall test environment shrinks drastically. The need for additional middleware is eliminated, costs are contained at the necessary minimum. With the latest firmThis feature offers a convenient way to e.g. trigger data logging based on environmental conditions or change measuring ranges according to the state of the unit under test. Imagine you would like to initiate logging data once a critical temperature threshold is exceeded at a certain location. To imple-



ware release, the LMG600 can also read information sent over the CAN bus and carry out a number of predefined actions based on its content. That is, the CAN bus interface of the power analyzer has become bi-directional, changing it from a purely passive sensor to a remote-controllable analysis tool. ment this procedure you simply would have the LMG600 read the information sent by the respective temperature sensor over CAN and set a trigger condition accordingly. Once the temperature has risen above the limit, recording starts automatically. Likewise, switching an electrical engine off via CAN could simultaneously trigger a range change in the power analyzer, avoiding the otherwise necessary settling period of the auto-ranging mechanism. The LMG600 allows to define up to 128 trigger conditions to cover automation of even the most sophisticated measurement and recording tasks.

Define actions for the LMG for incoming data of the CAN bus

#### Testing without disruption – five in one

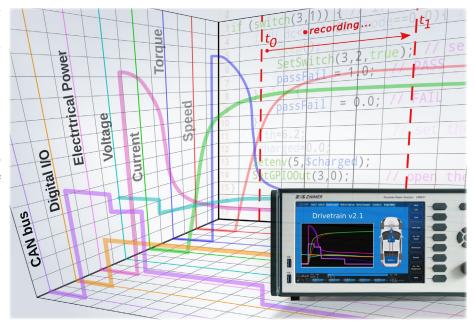
In a typical test scenario, the way from raw signals to the final pass/fail indication is a long and winding path stretching over five distinct phases. Computing RMS power is only one piece of the puzzle, and data from other sources might need to be integrated into the calculations. This can lead to a complex assortment of data sources and processing tools with many handover points. The discontinuities in the flow of data may require manual intervention, which demands time and effort and increases the risk of introducing errors.

The LMG671 is designed to combine all five phases of testing into a single instrument, thus eliminating unnecessary complexity, streamlining the testing process, making test engineers' life easier and keeping cost down.

1. **Signal acquisition**: the LMG671 goes beyond voltage and power. The versatile Process Signal Interface (PSI) can read virtually any analog or digital signal source, thus allowing e.g. temperature, pressure, speed, torque and other data to be collected together with voltage and current. No need to reconcile data points from different sources later on, no issues with inconsistent timestamps between variables.

2. **Timing control**: for the test results to be meaningful, the DUT needs to be observed in specific, predefined modes of operation. The LMG671 can control beginning and end of the measurements via the versatile Event Trigger option. In addition, it can react to external trigger inputs or CANbus commands to start recording data. The LMG671 can also control external devices via a number of analog and digital outputs in the optional PSI.

3. **Integration**: to calculate RMS voltage, current and power as well as harmonic values, the samples need to be summed over entire signal periods – this is the traditional domain of power analysis. (Outsourcing the calculation to PC environments already at this step renders the

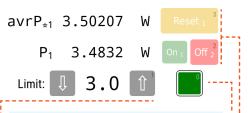


integrity of RMS values and harmonics vulnerable and makes calibration of the setup rather difficult.)

4. Derivation: in many applications, the measurement of electrical quantities is just a means to an end and not the final goal. An illustrative example is the qualification of inductive components: measuring voltage and current ultimately yields core losses and the peak values of magnetic field strength and flux density. Rather than exporting electric measurements to 3rd party applications for the calculation of the desired results, the LMG671 offers a powerful built-in programming language with a vast number of mathematical functions to carry out all required calculations in one fell swoop. No handover, no disruptions, no risk of additional errors.

5. **Pass/fail decision**: In case the DUT is tested against defined standards or previously established benchmarks, the pass/fail limits can be programmed into the LMG671 in order to allow the instrument to display the outcome of the test directly. Should there be different pass/fail criteria for consecutive DUTs, applicable limits can even be adjusted on-screen by the test engineer use the touchscreen GUI's input boxes or arrow keys. Some tests

require additional information (like e.g. magnetic path length, core diameter etc.) on the DUT that varies between tests and also needs to be considered for calculation. Also this kind of data can be entered and changed directly on-screen using a number of available input elements. These built-in decision-support features allow even less experienced or less well-trained users to reliably judge success or failure of the test.



#### Environment variables

In the example above, power P1 is compared to environment variable 1, which can be adjusted on-screen using the depicted arrow softkeys.

#### Signals

The values assumed by enviroment variables can be color-coded to alert the user to the status of the DUT or to indicate the outcome of the measurement e.g. pass/fail.

#### Switching keys

The status of the softkeys can be queried by the script. Those keys can act as push button, toggle or latching switches.

### Five in one example: automated magnetic core testing

↓ 20.0 1

↓ 25.0 1

Magn. Path length: 👢 100.0 m 👔

**Primary Current:** 

 $I_{prim} = 20.753 \text{ mA}$ 

6.5 m î

n<sub>prim</sub>:

Cross section:

Magnetic Flux Density:  $B_{pk} = 0.60800 \text{ T}$ Magnetic Field Strength:  $H_{pk} = 175.4024 \text{ A/m}$ 

CUSTOM View 1 Core Characteristics Electric Drive Wide vs. Narrow Device Example Test Script Editor

Core Losses:

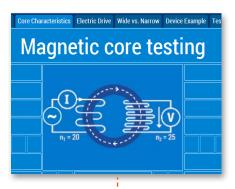
Passed

 $P_{fe} = 7.057 W$ 

Magnetic core testing

25 //Characteristics and loss 26 Pfe =p1111?\*\$n1/\$n2 //Powe 27 Bpk = urec1111?/(4\*fcyc111 magnetic flux density 28 Hpk = Ipk\*\$n1/\$lmagn // pe 29 ua = Bpk/0.0000012566/Hpk permeability

In this example the magnetic field strength and flux density from voltage, current and frequency measurements are calculated. The script editor offers a vast variety of mathematical, logical and procedural programming functions like loops and conditional execution of commands.



Make it easier to recognize your application: Add a meaningful title for your measurement. Use graphical elements like drawings or photographs to depict your setup and freely arrange them. Add your brand logo and reflect your corporate style in the choice of colors and design elements.

Sometimes, the formulae stored in the script editor require additional input, e.g. parameters that vary with every individual DUT, like material constants. No need to edit the stored scripts – these parameters can easily be entered on-screen by the executing engineer during testing. Arrow soft keys allow for in-/decrementing the chosen variables, and the number can be entered directly as well.

| n <sub>prim</sub> : | 20.0    |  |
|---------------------|---------|--|
| n <sub>sec</sub> :  | 25.0    |  |
| Cross section:      | 6.5 m   |  |
| Magn. Path length:  | 100.0 m |  |

Add measurement values you are interested in, and only show what you need. You can display any electric quantity measured by the power channels as well as values from any I/O interface (CAN, PSI, GPIO). Pass or fail criteria can be established in order to judge the suitability of the DUT for its intended purpose. The LMG600 allows to automate this decision based on the measured and calculated properties. The results of the test can be displayed in easily readable form to allow less skilled users to carry out testing without additional supervision.

Magnetic Flux Density:

Magnetic Field Strength:

 $H_{pk} = 175.4024 \text{ A/m}$ 

 $B_{pk} = 0.60800 T$ 

Secondary Voltage:

 $U_{sec} = 448.971 \text{ mV}$ 

Mode View

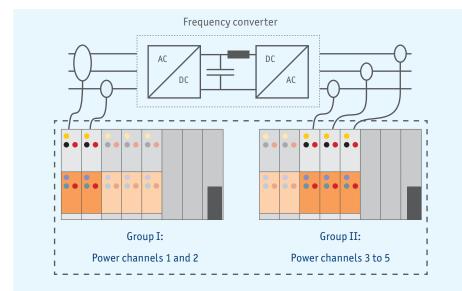
Copy Measurands

Passed

Primary Current: I<sub>prim</sub> = 20.753 mA

### Clear visualization of measurements thanks to groups

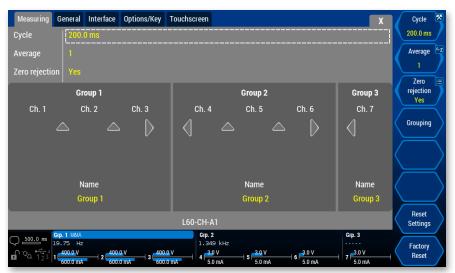
The power channels can be organized in groups that define their role in the current measurement application. The groups appear almost as virtual measurement channels or virtual devices in addition to the physical channels. The logical grouping of the P-channels is dependent on the number of wires and phases of the electrical system being analyzed. Thanks to the flexibility of the LMG600, it is possible to model even unusual and rarely seen configurations, such as split-phase systems and four-phase or multiphase systems. The only requirement is that all of the channels within a group have the same basic frequency and are of the same type (A, B, C). This will avoid subtle errors, which arise due to the different technical properties of the different channel types. One benefit of creating groups is that it makes configuring the device easier, since filter settings (for example) affecting all channels in the group only have to be configured once. In addition, derived values, such as active, apparent or idle power are calculated across all channels in the group. While grouping specifies how the channels are combined logically, the wiring dictates how the inputs of the measuring device are connected to the measuring circuit, i.e. whether it is a star-to-delta circuit or whether there are neutral wires, etc. The wiring defines how the measured signals are interpreted by the device.



This example shows in-/output measurements on a frequency converter using an LMG600 equipped with 5 power channels organised in two logical groups.

Group I measures the input power in an Aron circuit. C channels are usually sufficient.

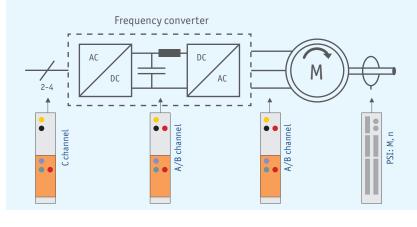
To determine the output power, Group II measures the voltages on the delta side and the currents on the star side. A channels are recommended for this.



This screenshot depicts an example for logical grouping of an LMG600 fitted with 7 power channels, e.g. for measuring an electric drive. Group 1 & 2, with three channels each, could comprise the 3-phase input/output connections, while the single-channel Group 3 might represent the DC link.

#### Electrical drive systems Application

More than half of the electrical energy generated worldwide is converted to mechanical motion, and the importance of electric powertrains for transport of goods and people is growing steadily. While outdated speed controllers are afflicted with losses of up to 40%, modern, frequency-controlled systems can achieve efficiency levels of over 95%. These frequency converters use pulse width modulation to control the speed of the motor with hardly any losses. The objective is to optimally adjust the converter and motor to one another, in order to achieve the best overall efficiency. Measuring the input power, the intermediate circuit, and the output power of the converter as well as the mechanical power of the motor simultaneously is anything but trivial. In addition to the integration of sensor technology (wideband sensors for high currents, high-voltage dividers, precise speed and torque transmitters), the instrument must meet the challenge of measuring the very steep-flanked signals at the converter output. This environment is often described as harsh, not merely from an EMC point of view.



#### Determining the efficiency of an electric drive system

C channels are usually sufficient for the input of the converter. Depending on the required level of precision, A or B channels are required for the DC intermediate circuit, as it exhibits significant residual ripple under certain circumstances.

For the converter output only A or B channels are to be used, also dependig on the required level of precision. Via a process interface mechanical quantities are measured synchronously to the other channels.

and another one on a filtered signal to de-

termine the power at certain frequencies,

resp. a subsequent FFT analysis to measure

the harmonic spectrum. This procedure is

very time-consuming, yet it cannot guaran-

tee that the conditions present during the

initial measurement still prevail during the

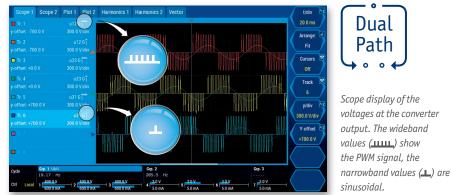
The innovative DualPath architecture of the

LMG600 provides all of the required results

simultaneously in a single measurement,

with maximum precision, and the widest

frequency range on the market - free from



Of course the key question in the analysis of electrical drive systems is: which part of the electrical energy at the converter output relates to the torque-relevant fundamental frequency of the motor, and which part to the remaining frequency range, particularly the harmonic spectrum? To give an accurate answer, it has long been necessary to perform two separate measurements: one without filters to establish the wideband power,

Dual

Path

#### CHALLENGES

- Synchronous measurement of speed and torque
- · Highly accurate measurement of the fundamental oscillation relevant to torque
- Simultaneous aliasing-free measurement of losses across maximum frequency range
- Range expansion for high current and medium voltage applications
- · Fast data export to third-party devices and applications

✓ DualPath

aliasing effects.

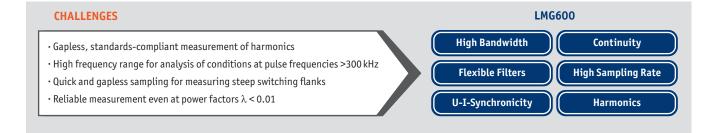
repetition.

- ✓ Accuracy
- ✓ A/B/C Channels  $\checkmark$ Immunity
- ✓ Harmonics ✓ Interfaces
- ✓ Star-to-Delta 1 Plug 'n' Measure

#### Application

#### Switched-mode power supplies

Already years ago, advances in power electronics have caused relatively large and heavy transformer power supplies to be replaced by smaller, lighter and more efficient switched mode power supplies. Today those can be found in practically all grid-powered electrical devices. While avoiding many of the downsides of their predecessors, they also bring new challenges: for one, the conducted emissions due to harmonics are not insignificant and must be limited by standards (EN61000-3-2, EN61000-3-12). Secondly, the high switching frequencies of up to several hundred kilohertz can lead to problems with electromagnetic compatibility, both on the grid side and on the consumers' part. The role of power measurement technology is to support the manufacturer in optimizing their products.



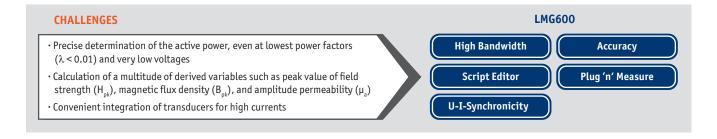
#### Application Solid & laminated magnetic cores

Under the influence of changing fields, the ferromagnetic components of an electrical machine are subject to losses due to continuous remagnetization and eddy currents, which are ultimately converted into heat or vibrations.

The total losses are frequency-dependent and should be minimized as far as possible, as they

have a significant effect (for example) on the range of the batteries in electric vehicles. The core power loss can be calculated directly from the excitation current of a test winding and the magnetization voltage of a sensor winding. The magnetic flux density in the core material can be derived from the rectified value of the voltage induced in the sensor winding. The magnetic field strength is proportional to the current flowing in the test winding.

While the high-frequency currents in solid cores can be measured directly, the high amp values occuring in laminated cores usually demand high-precision transducers.



#### Application

### Conformance testing for the aerospace industry

Particularly in the aerospace industry, electromagnetic compatibility between installed systems is of existential importance. For this reason, industry directives such as ABD0100.1.8 set limits on harmonic currents up to the range of 150 kHz. These harmonics can be analyzed using the LMG600. This can either be accomplished using the built-in harmonics analysis, or alternatively in any level of detail via off-line analysis of sample values using external software.

> to be continued on top of following page



### Application Lighting technology

In an effort to reduce energy consumption, light bulbs are being replaced with ever more efficient light sources all around the world. While on the consumer end all that is required is to insert a new product into the existing fitting, the differences on the electrical level are considerable – in contrast to conventional bulbs, LED lights and compact fluorescent lights ("low-energy light-bulbs") are controlled by special electronic ballasts. Some of these ballasts work with switching frequencies of up to 200 kHz and produce signal distortions at frequencies of up to 1 MHz. The manufacturers are required first and foremost to prevent damaging circuit feedback, and secondly, to ensure optimum service life for their products. To achieve the aforementioned objectives, often a controlled warm start is performed, whose proper execution has to be verified by making appropriate measurements.

Accuracy

**Ground Capacitance** 

LMG600

High Bandwidth

**Flexible Filters** 

**U-I-Synchronicity** 

#### CHALLENGES

- Broad frequency range of the measurement, hand-in-hand with a high level of precision
- · Verification of standby power of ballasts even for  $\lambda$  < 0.01
- Minimal earth capacitance to avoid leakage currents during the measurement

#### Application CE compliance testing for harmonics and flicker

Electrical equipment, systems and devices must satisfy the directives and ordinances of the EU on the permitted level of electromagnetic emissions and immunity to electromagnetic effects, if they are put on the market inside the European Union (EU). Two different types of grid emissions are tested: harmonics and flicker. Any electrical device with a non-linear load characteristic produces current harmonics. Due to the impedance of the grid, these cause drops in voltage and resulting distortions. In addition, certain devices (e.g. continuous-flow heaters, heating furnaces, et cetera) control their power consumption by abruptly switching on and off, which destabilizes the voltage level due to the grid impedance. This produces fluctuations in voltage, which trigger variations in brightness in the electric lighting ("flicker"). In combination with a suitable AC source and reference impedance, the LMG600 is the tool of choice for the qualified assessment of harmonics and flicker. The LMG Test Suite (see accessories) is providing a user-friendly software solution for this, which turns performing conformity tests for electromagnetic compatibility into child's play.



### Accuracy specification

| A channel  |                          |   |                               | :                        | ± (% of measure  | of measured value + % of maximum peak value)           |  |   |   |   |  |  |
|--|--------------------------|---|-------------------------------|--------------------------|--|--|--|---|---|---|--|--|
| Accuracy   | DC                       | DC <sup>e)</sup>                                  | 0.05 Hz 45 Hz<br>65 Hz 3 kHz  | 45 Hz 65 Hz              | 3 kHz 10 kHz   | 10 kHz<br>50 kHz                                       | 50 kHz<br>100 kHz  | 100 kHz<br>500 kHz  | 500 kHz1 MHz                              | f/1 MHz*0.7      f/1 MHz*1.0 +      f/1 MHz*1.8      -      f/1 MHz*1.8      f/1 MHz*1.4 +      f/1 MHz*1.3      f/1 MHz*1.4      f/1 MHz*1.4 <t< th=""><th>2 MHz 10 MHz</th></t<> | 2 MHz 10 MHz                             |  |
| Voltage U*   | 0.02+0.08                | 0.02+0.06 <sup>e)</sup>                           | 0.015+0.03                    | 0.01+0.02                | 0.03+0.06  | 0.2+   | 0.4  | 0.5+1.0   | 0.5+1.0                                   | f/1MHz*1.   | 5 + f/1 MHz*1.5                          |  |
| Voltage U <sub>SENSOR</sub>                              | 0.02+0.08                | 0.02+0.06 e)                                      | 0.015+0.03                    | 0.01+0.02                | 0.03+0.06  | 0.2+   | 0.4  | 0.4+0.8   | 0.4+0.8                                   | f/1MHz*0.   | 7 + f/1 MHz*1.5                          |  |
| Current I*<br>5 mA5 A                                    | 0.02+0.1                 | 0.02+0.06 <sup>e)</sup>                           | 0.015+0.03                    | 0.01+0.02                | 0.03+0.06  | 0.2+   | 0.4  | 0.5+1.0   | 0.5+1.0                                   |   | -  |  |
| Current I*<br>10 A32 A                                   | 0.02+0.1 <sup>1)</sup>   | -   | 0.015+0.033)                  | 0.01+0.02 <sup>3)</sup>  | 0.1+0.2 <sup>3)</sup>  | 0.3+0.6 <sup>3)</sup>                                  |  | 00 kHz*0.8 +<br>00 kHz*1.2 <sup>3)</sup>  | -   | -   | -  |  |
| Current I <sub>SENSOR</sub>                              | 0.02+0.08                | 0.02+0.06 <sup>e)</sup>                           | 0.015+0.03                    | 0.01+0.02                | 0.03+0.06  | 0.2+   |  | 0.4+0.8   | 0.4+0.8                                   | f/1MHz*0.   | 7 + f/1 MHz*1.5                          |  |
| Power U*/ I*<br>5 mA5 A                                  | 0.032+0.09               | 0.032+0.06 e)                                     | 0.024+0.03                    | 0.015+0.01               | 0.048+0.06   | 0.324  | -0.4   | 0.8+1.0   | 0.8+1.0                                   | 1 · · ·   | -  |  |
| Power U*/ I*<br>10 A32 A                                 | 0.032+0.09 <sup>2)</sup> | -   | 0.024+0.034)                  | 0.015+0.01 <sup>4)</sup> | 0.104+0.134)   | 0.4+0.54)  |  | f/100 kHz*1.0 +<br>f/100 kHz*1.14)  | -   | -   | -  |  |
| Power U*/ I <sub>sensor</sub>                            | 0.032+0.08               | 0.032+0.06 e)                                     | 0.024+0.03                    | 0.015+0.01               | 0.048+0.06   | 0.324  | -0.4   | 0.72+0.9  | 0.72+0.9                                  | f/1MHz*1.   | 3+f/1MHz*1.5                             |  |
| Power U <sub>sensor</sub> / I*<br>5 mA5 A                | 0.032+0.09               | 0.032+0.06 e)                                     | 0.024+0.03                    | 0.015+0.01               | 0.048+0.06   | 0.324  | -0.4   | 0.72+0.9  | 0.72+0.9                                  |   | -  |  |
| Power U <sub>SENSOR</sub> / I*<br>10 A32 A               | 0.032+0.09 <sup>2)</sup> | -   | 0.024+0.034)                  | 0.015+0.01 <sup>4)</sup> | 0.104+0.134)   | 0.4+0.54)  |  | f/100 kHz*1.0 +<br>f/100 kHz*1.0 <sup>4</sup> )   | -   | -   | -  |  |
| Power $\rm U_{\rm SENSOR}/\rm I_{\rm SENSOR}$            | 0.032+0.08               | 0.032+0.06 e)                                     | 0.024+0.03                    | 0.015+0.01               | 0.048+0.06   | 0.324  | -0.4   | 0.64+0.8  | 0.64+0.8                                  | f/1 MHz*1.  | L+f/1MHz*1.5                             |  |
| B channel  |                          | ± (% of measured value + % of maximum peak value) |                               |                          |  |  |  |   |   |   |  |  |
| Accuracy   | DC                       |   | 0,05 Hz 45 Hz<br>65 Hz 1 kHz  | 45 Hz                    | 65 Hz  | 1 kHz 5 kH   | z  | 5 kHz 20 kHz  | 20 kHz 1                                  | 00 kHz  | 100 kHz<br>500 kHz                       |  |
| Voltage U*   | 0.1+0.1                  |   | 0.1+0.1                       | 0.034                    | +0.03  | 0.2+0.2  |  | 0.3+0.4   | 0.4+0.                                    | 8 1 1   | /100 kHz*0.8 +<br>f/100 kHz*1.2          |  |
| Current I* 5 mA5 A<br>Current I <sub>SENSOR</sub>        | 0.1+0.1                  |   | 0.1+0.1                       | 0.03+                    | +0.03  | 0.2+0.2  |  | 0.3+0.4   | 0.4+0.                                    | 8 1 1   | /100 kHz*0.8 +<br>f/100 kHz*1.2          |  |
| Current I*<br>10 A32 A                                   | 0.1+0.1                  | I)  | 0.1+0.13)                     | 0.03+                    | 0.033)   | 0.2+0.2 <sup>3</sup> ) 0.6+1.2 <sup>3</sup> ) 1.5+1.   |  | h <sup>-y</sup>   '   | /100kHz*2.0+<br>/100kHz*2.0 <sup>3)</sup> |   |  |  |
| Power U*/ I*<br>5 mA5 A<br>Power U*/ I <sub>SENSOR</sub> | 0.16+0.7                 | 1   | 0.16+0.1                      | 0.05+                    | 0.05+0.02 0.32+0.2 0.48+0.4  |  | 0.48+0.4   | 0.64+0  | 1.8 1 1                                   | ′100kHz*1.28+<br>f/100kHz*1.2   |  |  |
| Power U*/ I*<br>10A32A                                   | 0.16+0.1                 | 2)  | 0.16+0.14)                    | 0.05+                    | +0.02 <sup>4</sup> ) 0.32+0.2 <sup>4</sup> ) 0.72+0.8 <sup>4</sup> ) |  | 0.05+0.02 <sup>4</sup> ) 0.32+0.2 <sup>4</sup> ) 0.72+0.8 <sup>4</sup> ) 1.52+1.19 |   | 15*/ / '                                  | /100kHz*2.24+<br>/100kHz*1.64   |  |  |
| C channel  |                          |   |                               | ±                        | (% of measure  | d value + % of n                                       | 1aximum pe   | ak value)   |   |   |  |  |
| Accuracy   | DC                       |   | 0,05 Hz 45 Hz<br>65 Hz 200 Hz | 45 Hz                    | 65 Hz  | 200 Hz 500 I   | Hz   | 500 Hz 1 kHz  | 1 kHz 2                                   | 2 kHz   | 2 kHz 10 kHz                             |  |
| Voltage U*   | 0.1+0.1                  |   | 0.02+0.05                     | 0.024                    | +0.02  | 0.05+0.05  |  | 0.2+0.1   | 1.0+0                                     | .5  | f/1kHz*1.0 +<br>f/1kHz*1.0               |  |
| Current I*   | 0.1+0.1                  | )   | 0.02+0.05 <sup>3)</sup>       | 0.02+                    | 0.023)   | 0.05+0.053)  |  | 0.2+0.1 <sup>3)</sup>   | 1.0+0.                                    | 5 <sup>3)</sup>   | f/1kHz*1.0 +<br>f/1kHz*1.0 <sup>3)</sup> |  |
| Current I <sub>sensor</sub>                              | 0.1+0.1                  |   | 0.02+0.05                     | 0.024                    | +0.02  | 0.05+0.05  |  | 0.2+0.1   | 1.0+0                                     | .5  | f/1kHz*1.0 +<br>f/1kHz*1.0               |  |
| Power  | 0.16+0.1                 | 2)  | 0.032+0.05 <sup>4)</sup>      | 0.03+                    | 0.014)   | 0.08+0.054)  |  | 0.32+0.14)  | 1.6+0.                                    | 54)   | f/1kHz*1.6 +<br>f/1kHz*1.0 <sup>4)</sup> |  |
| Accuracies valid for:                                    | 2. Am<br>3. Wa<br>4. The | bient temperat<br>rm-up time 1 h<br>maximum pea   |                               |                          |  |  |  | 5. $0 \le \lambda \le 1$ (pow<br>6. Current and vo<br>7. Adjustment can<br>8. Calibration int | ltage 10 % 110<br>rried out at 23 °C      | % of nominal val  |  |  |
| Other values   |                          | A   | Ill other values are          | calculated from          | -  | e and power. Acc<br>[ * U, $\Delta$ S / S = $\Delta$ I |  | error limits are deriv  | ved according to c                        | ontext  |  |  |

 $^{\scriptscriptstyle (1)\,2)\,3)\,4)}$  only valid in range 10 ... 32 A:

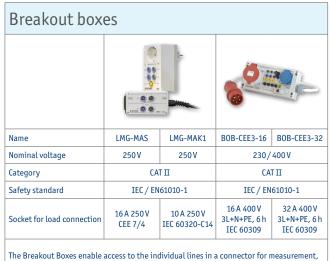
<sup>1)</sup>additional uncertainty  $\pm \frac{50 \,\mu\text{A}}{A^2} * \text{I}_{trms^2}$  <sup>2)</sup>additional uncertainty  $\pm \frac{50 \,\mu\text{A}}{A^2} * \text{I}_{trms^2} * \text{U}_{trms}$  <sup>3)</sup>additional uncertainty  $\pm \frac{50 \,\mu\text{A}}{A^2} * \text{I}_{trms^2} * \text{U}_{trms}$  <sup>4)</sup>additional uncertainty  $\pm \frac{50 \,\mu\text{A}}{A^2} * \text{I}_{trms^2} * \text{U}_{trms}$  <sup>a)</sup>additional uncertainty  $\pm \frac{50 \,\mu\text{A}}{A^2} * \text{I}_{trms^2} * \text{U}_{trms}$  <sup>b)</sup>Accuracy specification after non-persistent zero adjustment, temperature change after zero adjustment max.  $\pm 1^{\circ}\text{C}$ 

| Voltage measuring ranges U*   |   |  |   |   |   |             |               |               |              |              |            |              |           |      |
|---|---|--|---|---|---|-------------|---------------|---------------|--------------|--------------|------------|--------------|-----------|------|
| Nominal value (V)   | 3   |  | 6   | 12.5  | 25                                      |             | 60            | 130           |              | 250          | 400        | 600          | 0         | 1000 |
| Max. trms value (V)   | 3.3   |  | 6.6   | 13.8  | 27.5                                    |             | 66            | 136           |              | 270          | 440        | 660          |           | 1000 |
| Max. peak value (V)   | 6   |  | 12  | 25  | 50                                      |             | 100           | 200           |              | 400          | 800        | 160          |           | 3200 |
| Overload protection   |   |  |   |   |   | + 10 % co   | ntinuously, 1 |               |              |              |            | 100          |           | 5200 |
| Input impedance   |   |  |   |   | 10001                                   | . 10 /0 00  |               | Ω, 4pF        |              | 20113        |            |              |           |      |
| Earth capacitance   |   |  |   |   |   |             |               | 0pF           |              |              |            |              |           |      |
|   |   |  |   |   |   |             |               |               |              |              |            |              |           |      |
| Current measuring ranges I*   |   |  |   |   |   |             |               |               |              |              |            |              |           |      |
| Nominal value (A)   | 0.005   | 0.01   | 0.02  | 0.04  | 0.08                                    | 0.15        | 0.3           | 0.6           | 1.2          | 2.5          | 5          | 10           | 20        | 32   |
| Max. trms value (A)   | 0.0055  | 0.011  | 0.022   | 0.044   | 0.088                                   | 0.165       | 0.33          | 0.66          | 1.32         | 2.75         | 5.5        | 11           | 22        | 32   |
| Max. peak value (A)   | 0.014   | 0.028  | 0.056   | 0.112   | 0.224                                   | 0.469       | 0.938         | 1.875         | 3.75         | 7.5          | 15         | 30           | 60        | 120  |
| Input impedance   | ca. 2   | .2Ω  |   | ca. 600 mΩ  |   |             | ca.80 mΩ      |               |              | ca. 20 mΩ    |            |              | ca. 10 mΩ |      |
| Overload protection permanent (A)   |   |  |   | LMG in ope  | ration 10 A                             |             |               |               |              |              | LMG in ope | eration 32 A |           |      |
| Overload protection short-time (A)  |   |  |   |   |   |             | 150 A fo      | or 10 ms      |              |              |            |              |           |      |
| Earth capacitance   |   |  |   |   |   |             | < 9           | 0pF           |              |              |            |              |           |      |
| Sensor inputs U <sub>SENSOR</sub> , I <sub>SENSOR</sub>   |   |  |   |   |   |             |               |               |              |              |            |              |           |      |
| Nominal value (V)   | 0.0   | 3  | 0.06  |   | 0.12                                    |             | 0.25          | 0.5           | ;            | 1            |            | 2            |           | 4    |
| Max. trms value (V)   | 0.03  | 3  | 0.066   |   | 0.132                                   |             | ).275         | 0.5           | 5            | 1.1          |            | 2.2          |           | 4.4  |
| Max. peak value (V)   | 0.09  | 77   | 0.1953  |   | 0.3906                                  | 0           | .7813         | 1.56          | i3           | 3.125        |            | 6.25         |           | 12.5 |
| Overload protection   | 100V continuously, 250V for 1 s   |  |   |   |   |             |               |               |              |              |            |              |           |      |
| Input impedance   |   | 100 kΩ, 34 pF  |   |   |   |             |               |               |              |              |            |              |           |      |
| Earth capacitance   | < 90 pF   |  |   |   |   |             |               |               |              |              |            |              |           |      |
| Isolation   |   | All current and voltage inputs are isolated against each other, against remaining electronics and against earth.<br>Max. 1000 V / CAT III resp. 600 V / CAT IV |   |   |   |             |               |               |              |              |            |              |           |      |
| Synchronization   |   | le filters. Th   |   | n the signal p<br>dings are very  |   |             |               |               |              |              |            |              |           |      |
| Scope function  | Graphical   | lisplay of sa  | mple value  | s over time in  | two scopes v                            | /ith 8 sign | als each      |               |              |              |            |              |           |      |
| Plot function   | Two time (  | rend-) diag  | rams of ma  | x. 8 paramete   | rs each, max                            | . resolutio | n 10 ms       |               |              |              |            |              |           |      |
| External graphics interface (L671-OPT-DVI)  | DVI interfa   | ce for exter   | nal screen (  | output  |   |             |               |               |              |              |            |              |           |      |
| Process signal interface (L6-OPT-PSI)   | 8 analog ir<br>32 analog<br>8 switching<br>8 switching                    | outputs (ou<br>outputs (6<br>outputs (15   | /s, 16 bit, D<br>tput per cyc<br>switches w<br>0 kS / s, in t | bit, BNC)<br>-Sub:DE-09)<br>Sle, 14 bit, D-S<br>ith 2 connect<br>two groups 4 i<br>(150 kS/s, D-  | ions each an<br>nputs each v            | d 2 switch  |               |               |              | D-Sub: DB-2! | 5)         |              |           |      |
| Star-delta conversion (L6-OPT-SDC)  | Conversion  | of line volt   | ages to pha   | ise voltages a  | nd computat                             | ion of resu | lting active  | power         |              |              |            |              |           |      |
| Harmonics at device level (L6-OPT-HRM)  | Harmonics   | and interha  | rmonics up  | to 2,000th or   | der, independ                           | lent and si | multaneousl   | y for each gr | oup          |              |            |              |           |      |
| CE Harmonics (L6-OPT-HRM)   | According   | to IEC EN 61   | 000-4-7   |   |   |             |               |               |              |              |            |              |           |      |
| Flicker (L6-OPT-FLK)  | According   | to IEC EN 61   | 000-4-15  |   |   |             |               |               |              |              |            |              |           |      |
| LMG Remote  | LMG600 ex   | pansion sof  | tware, basi   | c module for 1  | remote confi                            | guration a  | nd operation  | n via PC      |              |              |            |              |           |      |
| LMG Test Suite  | IEC EN 610<br>IEC EN 610  | 00-3-2 & 61<br>00-3-3 & 61   | 000-3-12 fc<br>000-3-11 fc                                    | ests accordin<br>or harmonics (<br>or flicker (LMG<br>/ power (LMG-                               | (LMG-TEST-CI<br>i-TEST-CE-FLI           | <)          |               |               |              |              |            |              |           |      |
| Miscellaneous<br>Dimensions<br>Display<br>Weight<br>Protection class<br>Electromagnetic compatibility<br>Temperature<br>Climatic category<br>Line input | 10.1", 128<br>Depending<br>EN 61010 (<br>EN 61326<br>5 40 °C<br>Normal en | 0 x 800 px<br>on installe<br>IEC 61010, N<br>(operation)<br>vironmenta   | d options: r<br>/DE 0411), r<br>/ -20 50<br>L conditions      | xD) 433 mm x<br>nax. 18.5 kg fr<br>protection cla<br>°C (storage)<br>according to<br>0 W for LMG6 | or LMG671<br>ss I / IP20 in<br>EN 61010 |             |               |               | x 4 RU x 590 | lmm          |            |              |           |      |

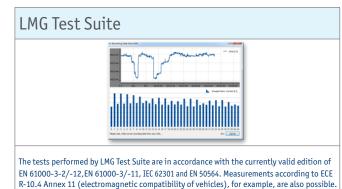
### Accessories program (excerpt)

| Current senso          | rs  |                          |                          |                           |   |                         |                     |                                       |
|------------------------|---|--------------------------|--------------------------|---------------------------|---|-------------------------|---------------------|---------------------------------------|
| Туре                   | Ring-type transducers      Current clamps |                          |                          |                           |   |                         |                     | Shunt                                 |
|                        |   | 0                        | DANIJENSE                |                           |   |                         | 0                   | 10                                    |
| Name                   | РСТ                                       | Hallxxx-L6               | DS                       | WCT                       | LMG-Z5XX                                  | L60-Z406,<br>L60-Z60/66 | L60-Z68             | LMG-SH (-P)                           |
| Signal type            |   | AC+DC                    |                          |                           | AC  | AC                      | AC+DC               | AC+DC                                 |
| Current ranges         | 2002000 A <sub>rms</sub>                  | 1002000 A <sub>rms</sub> | 50 7000 A <sub>rms</sub> | 100 1000 A <sub>rms</sub> | 750 A <sub>rms</sub> 10 kA <sub>rms</sub> | 403 kA <sub>rms</sub>   | 1 kA <sub>rms</sub> | 22mA <sub>rms</sub> 1A <sub>rms</sub> |
| Best accuracy          | 0.01%                                     | 0.5%                     | 0.01%                    | 0.25%                     | 0.02%                                     | 0.2%                    | 2.0%                | 0.15%                                 |
| Max. bandwidth         | DC 1 MHz                                  | DC100 kHz                | DC1MHz                   | 30 Hz 1 MHz               | 15 Hz5 kHz                                | 5 Hz50 kHz              | DC 2 kHz            | DC 100 kHz                            |
| Power supply by LMG600 | PCT200/600                                | Yes                      | No                       | Not                       | required                                  | Ye                      | 25                  | Not required                          |
| Plug 'n' Measure       | PCT200/600                                | Yes                      | No                       |                           | No  | Ye                      | 25                  | No                                    |





The Breakout Boxes enable access to the individual lines in a connector for measurement, and provide an easy and elegant way to take measurements on single and three-phase consumers.



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The LMG Remote PC software allows to easily control the LMG600 remotely from a Win-

dows PC. Since this software mimicks the measuring device itself down to the last detail, the LMG600 can be operated as usual, even from the PC - no rethinking required, no

LMG Remote

familiarization time.

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# LMG671 en 12/2019